Stripping multiple laters, one step at a time Introducing the "step-taking modality"

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The presentation addresses the following:

- ► A brief coverage of what the later modality (the "later") is
- The ongoing story about adding and stripping more and more laters
- > The challenges regarding laters with respect to expressivity and presentation

Please do: ask questions, add missing clarifications, provide running feedback

What are laters?

Structural recursion through program steps (step-indexing):

LATER-INTRO	LATER-MONO	HT-FRAME-LATER
Р	$P \vdash Q$	$\{P\} e \{w. Q\}$
$\overline{\triangleright P}$	$\overline{{\triangleright} P \vdash {\triangleright} Q}$	$\overline{\{P \ast \triangleright R\} e \{w. Q \ast R\}}$

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Higher-order ghost state (such as Invariants and propositional agreement):

$$\frac{\text{HT-INV-OPEN}}{e \text{ is atomic}} \{ \triangleright P * Q \} e \{ w. \triangleright P * R \}}{\{ P * Q \} e \{ w. R \}} \qquad \qquad \frac{\text{HO-AGREE}}{[ag(P)]^{\gamma}} [ag(Q)]^{\gamma}}{\triangleright (P = Q)}$$

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"Co-inductive" definitions:

$$\texttt{is_stream} \triangleq \mu X \ \ell. \ (\ell = \texttt{inl}()) \lor (\exists v, \ell'. \ \ell = \texttt{inr}(v, \ell') \ast \triangleright X \ \ell')$$

People started putting them in various (sound) places, and they started to crop up in presented abstract specifications (ghost theories):

 $\frac{\Pr \text{CTO-RECV-R}}{\Pr \text{ot_ctx } \chi ([w] \cdot \vec{v_1}) \vec{v_2} * \operatorname{prot_own_r} \chi (?\vec{x}: \vec{\tau} \langle v \rangle \{P\}. \operatorname{prot})}{\Rightarrow \forall \exists \vec{y}. (w = v[\vec{y}/\vec{x}]) * P[\vec{y}/\vec{x}] * \operatorname{prot_ctx} \chi \vec{v_1} \vec{v_2} * \operatorname{prot_own_r} \chi \operatorname{prot}[\vec{y}/\vec{x}]}$

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Expressivity: Fine! We do take a step whenever we use the ghost theory **Presentation:** How do we explain this specification to newcomers (and reviewers)?

"Dont think about it"

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"We can just get rid of it, when we take a step"

But then the problem multiplied.

Multiple laters

People started putting even more laters in (sound) places.

PROTO-ALLOC $\models \exists \chi. \operatorname{prot_ctx} \chi \ \epsilon \ \epsilon * \operatorname{prot_own}_{\mathsf{I}} \chi \ \operatorname{prot} * \operatorname{prot_own}_{\mathsf{r}} \chi \ \overline{prot}$ PROTO-SEND-L $\operatorname{prot_ctx} \chi \ v_1^{\mathsf{r}} \ v_2^{\mathsf{r}} * \operatorname{prot_own}_{\mathsf{I}} \chi \ (! \ \vec{x} : \vec{\tau} \ \langle v \rangle \{P\}. \ \operatorname{prot}) * P[\vec{t}/\vec{x}]$ $\xrightarrow{\mathsf{PROTO-SEND-L}}_{|\overrightarrow{\mathsf{prot_ctx}} \chi \ (v_1^{\mathsf{r}} \cdot [v[\vec{t}/\vec{x}]]) \ v_2^{\mathsf{r}} * \operatorname{prot}_{\mathsf{own}_{\mathsf{I}}} \chi \ (\operatorname{prot}) * P[\vec{t}/\vec{x}]$ $\xrightarrow{\mathsf{PROTO-SEND-L}}_{|\overrightarrow{\mathsf{prot_ctx}} \chi \ (v_1^{\mathsf{r}} \cdot [v[\vec{t}/\vec{x}]]) \ v_2^{\mathsf{r}} * \operatorname{prot_own}_{\mathsf{I}} \chi \ (\operatorname{prot}) * P[\vec{t}/\vec{x}])$ $\xrightarrow{\mathsf{PROTO-SEND-L}}_{|\overrightarrow{\mathsf{prot_ctx}} \chi \ (v_1^{\mathsf{r}} \cdot [v[\vec{t}/\vec{x}]]) \ v_2^{\mathsf{r}} * \operatorname{prot_own}_{\mathsf{r}} \chi \ (\operatorname{prot}[\vec{t}/\vec{x}])}$ $\xrightarrow{\mathsf{PROTO-RECV-R}}_{\mathsf{prot_ctx} \chi \ ([w] \cdot v_1^{\mathsf{r}}) \ v_2^{\mathsf{r}} * \operatorname{prot_own}_{\mathsf{r}} \chi \ (?\vec{x} : \vec{\tau} \ \langle v \rangle \{P\}. \ \operatorname{prot})$ $\xrightarrow{|\overrightarrow{\mathsf{prot_ctx}} \chi \ ([w] \cdot v_1^{\mathsf{r}}] * \operatorname{prot_ctx} \chi \ v_1^{\mathsf{r}} \ v_2^{\mathsf{r}} * \operatorname{prot_own}_{\mathsf{r}} \chi \ \operatorname{prot}[\vec{v}/\vec{x}]}$

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Expressivity: We can just synchronise using a physical lock and take many more steps!

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Expressivity: We can just synchronise using a physical lock and take many more steps! **Presentation:** How do we present this to newcomers (and reviewers)???

You roll up your sleeves ..

The need for skip instructions. The rules PROTO-SEND-L and PROTO-SEND-R from Figure 20 contain a number of later modalities (>) proportional to the other endpoint's buffer. As explained in § 9.3 these later modalities are the consequence of having to perform a number of case analyses on the subprotocol relation, which is defined using guarded recursion, and thus contains a later modality for each recursive unfolding.

To eliminate these later modalities, we instrument the code of the send function with the skipN (llength r) instruction, which performs a number of skips equal to the size of the other endpoint's buffer r. The skipN instruction has the following specification:

 $\{ \triangleright^n P \} \texttt{skipN} \; n \; \{ P \}$

Instrumentation with skip instructions is used often in work on step-indexing, see e.g., [SSB16; GST^+20]. Instrumentation is needed because current step-indexed logics like Iris unify physical/program steps and logical steps, *i.e.*, for each physical/program step at most one later can be eliminated from the hypotheses. In recent work by Svendsen *et al.* [SSB16], Matsushita and Jourdan [MJ20], and Spies *et al.* [SGG⁺21] more liberal versions of step-indexing have been proposed, but none of these versions of step-indexing have been integrated into the main Coq development of Iris and HeapLang.

But what if you can only take one step? e.g. if you have to put your ghost state in an invariant

People came up with clever solutions to strip multiple laters during one step!

$$\begin{array}{ll} \text{HT-STEP-GET} \\ \underline{\{P * \Xi \ 0\} \ e \ \{\Phi\}} \\ \hline \{P\} \ e \ \{\Phi\} \end{array} & \begin{array}{ll} \text{HT-STEP-INCR} \\ \underline{\{P\} \ e \ \{w. \ Q\}} \\ \hline \{P\} \ e \ \{w. \ Q\} \end{array} & \begin{array}{ll} \text{HT-STEP-FRAME} \\ \hline \{P\} \ e \ \{w. \ Q\} \\ \hline \{P * \Xi \ n\} \ e \ \{w. \ Q * \Xi \ n+1\} \end{array} & \begin{array}{ll} \text{HT-STEP-FRAME} \\ \hline \{P\} \ e \ \{w. \ Q\} \end{array} \\ \hline \{P * \Xi \ n * \rhd^n \ R\} \ e \ \{w. \ Q * R\} \end{array}$$

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Expressivity: We can strip all the laters we need, by tracking a step lower bound inside our invariant that grows in tandem with our ghost state, so we can guarantee that we can always strip the appropriate laters using Ht-step-frame, while updating the lower bound at every step using Ht-step-incr!

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Ht-step-get	Ht-step-incr	Ht-step-frame	STEP-DUP
$\{P st \ ip; \ e angle \ \{\Phi\}$	$\{P\}\langle ip; e\rangle \{w, Q\}$	$\{P\}\langle ip; e\rangle \{w, Q\}$	X n
$\{P\}\langle ip; e\rangle \{\Phi\}$	$\overline{\{P * \mathbb{Z} n\} \langle ip; e \rangle \{w. Q * \mathbb{Z} n + 1\}}$	$\overline{\{P * \mathbb{Z} n * \triangleright^n R\}} \langle ip; e \rangle \{w. Q * R\}$	$\overline{X n * X n}$

Fig. 12. The mechanism for stripping multiple laters. We require *e* to be an atomic expression.

The shared logical context can then be captured as the following Iris invariant:

 $\exists Tl, Tr, Rl, Rr. auth_list \chi_{T1} Tl * auth_list \chi_{Tr} Tr * auth_list \chi_{R1} Rl * auth_list \chi_{Rr} Rr * prot_ctx \chi_{chan} (Tl - Rr) (Tr - Rl) * Rr \leq_p Tl * Rl \leq_p Tr * X |Tl| * X |Tr|$

Stripping multiple laters. In Iris, and thus Aneris, one can strip a later whenever a step of computation is taken. Conventionally the intuition is that one step equates stripping one later. However, recent discoveries [Matsushita et al. 2022; Mével et al. 2019; Spies et al. 2022] uncovered various methods for stripping *multiple* laters per step. Based on these discoveries we extended Aneris with a similar, albeit more simplistic, mechanism as presented in Figure 12. The mechanism lets us strip multiple laters during one physical step, based on the amount of steps that has been taken thus far. The rule HT-STEP-GET lets us track a new lower bound of steps taken thus far X 0, and HT-STEP-INCR allows us to increase it by one, every time a step is taken. Crucially, the rule HT-STEP-INCR and the step is taken the lower bound of steps taken the step is taken.

What is the problem?

There is currently no way to present specification patterns without the context of the later-stripping mechanism.

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WISHFUL-PROTO-ALLOC

 $\exists \chi$. prot_ctx $\chi \in \epsilon * \text{prot_own} \ \chi \text{ prot} * \text{prot_own} \ \chi \text{ prot}$

WISHFUL-PROTO-SEND-L prot_ctx $\chi \vec{v_1} \vec{v_2} * \text{prot}_own_l \chi (! \vec{x} : \vec{\tau} \langle v \rangle \{P\}, \text{prot}) * P[\vec{t}/\vec{x}]$

prot_ctx χ $(\vec{v_1} \cdot [v[\vec{t}/\vec{x}]])$ $\vec{v_2} * \text{prot}_own_1 \chi$ $(prot[\vec{t}/\vec{x}])$

WISHFUL-PROTO-RECV-R prot_ctx χ ([w] $\cdot \vec{v_1}$) $\vec{v_2} * \text{prot_own}_r \chi$ (? $\vec{x} : \vec{\tau} \langle v \rangle \{P\}$. prot)

 $\exists \vec{y}. (w = v[\vec{y}/\vec{x}]) * P[\vec{y}/\vec{x}] * \text{prot}_{\text{ctx}} \chi \vec{v_1} \vec{v_2} * \text{prot}_{\text{own}} \chi \vec{v} \tau \vec{v} \vec{v} \vec{v}$

Solution: Introducing the step-taking modality!

$\mid \sim P$

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Recovers the intuition that we can get *P* after taking a step:

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$\rightsquigarrow P$

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Intentionally looks like the original later-stripping rule:

 $\frac{\text{HT-LATER-FRAME}}{\{P\} e \{w. Q\}}$ $\frac{\{P\} e \{w. Q\}}{\{P * \triangleright R\} e \{w. Q * R\}}$

The step-taking modality can be used to express the later-stripping mechanism as an abstract specification pattern (rather than via Hoare triples):

Step-step-get $\rightarrowtail X 0$	$\frac{\mathbb{X} n}{\searrow \mathbb{X} n+1}$	$\frac{\text{STEP-STEP-FRAME}}{[] \stackrel{\boxtimes}{\longrightarrow} P}$
	$\frac{\text{Ht-step-modality}}{\{P\} e \{w. Q\}}$ $\frac{\{P \models \forall w. Q\}}{\{P \models \forall w. Q \models R\} e \{w. Q \models R\}}$	

These rules supercede the former Hoare triple rules for the later-stripping mechanism

Abstract specifications of ghost theory

We can derive abstractions with the step-taking modality on top of each other:

prot_ctx_step $\chi \vec{v_1} \vec{v_2} \triangleq$ prot_ctx $\chi \vec{v_1} \vec{v_2} * \mathbb{E} |\vec{v_1}| * \mathbb{E} |\vec{v_2}|$

STEP-PROTO-ALLOC $\mapsto \exists \chi. \text{prot_ctx_step } \chi \in \epsilon * \text{prot_own}_{I} \chi \text{ prot } * \text{prot_own}_{r} \chi \overline{\text{prot}}$

STEP-PROTO-SEND-L prot_ctx_step $\chi \vec{v_1} \vec{v_2} * \text{prot}_own_l \chi (!\vec{x}: \vec{\tau} \langle v \rangle \{P\}, \text{prot}) * P[\vec{t}/\vec{x}]$

 \mapsto prot_ctx_step χ $(\vec{v_1} \cdot [v[\vec{t}/\vec{x}]]) \vec{v_2} * \text{prot_own} \chi$ $(\text{prot}[\vec{t}/\vec{x}])$

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STEP-PROTO-RECV-R prot_ctx_step χ ($[w] \cdot v_1$) v_2 * prot_own_r χ ($?\vec{x} : \vec{\tau} \langle v \rangle \{P\}$. prot) $\mapsto \exists \vec{y}. (w = v[\vec{y}/\vec{x}]) * P[\vec{y}/\vec{x}] * \text{prot}_{ctx_step} \chi \vec{v_1} \vec{v_2} * \text{prot}_{own_r} \chi \text{ prot}[\vec{y}/\vec{x}]$

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STEP-PROTO-RECV-R

prot_ctx_step χ ($[w] \cdot v_1$) v_2 * prot_own_r χ ($?\vec{x} : \vec{\tau} \langle v \rangle \{P\}$. prot)

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 $\texttt{prot_ctx_step} \ \chi \ \vec{v_1} \ \vec{v_2} \triangleq \texttt{prot_ctx} \ \chi \ \vec{v_1} \ \vec{v_2} * \mathbb{X} \ |\vec{v_1}| * \mathbb{X} \ |\vec{v_2}|$

STEP-PROTO-ALLOC $\vdash \exists \chi. prot_ctx_step \ \chi \ \epsilon \ \epsilon * prot_own_I \ \chi \ prot * prot_own_r \ \chi \ \overline{prot}$

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 $\rightarrowtail \texttt{prot_ctx_step } \chi (\vec{v_1} \cdot [v[\vec{t}/\vec{x}]]) \ \vec{v_2} * \texttt{prot_own}_{\mathsf{I}} \ \chi \ (\textit{prot}[\vec{t}/\vec{x}])$

Step-proto-recv-r

 $\texttt{prot_ctx_step} \ \chi \ ([w] \cdot \vec{v_1}) \ \vec{v_2} * \texttt{prot_own}_r \ \chi \ (?\vec{x} : \vec{\tau} \ \langle v \rangle \{P\}. \ \textit{prot})$

Expressivity: Fine! We do take a step whenever we use the ghost theory **Presentation:** How do we explain this specification to newcomers (and reviewers)?

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Derived abstractions may hide the number of laters that is needed to be stripped

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SESCROW-INIT $\Rightarrow \exists \chi. \text{ ses_own } \chi \text{ left } 0 \text{ } 0 \text{ } \text{prot } * \text{ ses_own } \chi \text{ right } 0 \text{ } 0 \text{ } \overline{\text{prot}}$

 $\frac{\operatorname{ses_own} \chi \ s \ n \ m \left(! \left(\vec{x} : \vec{\tau}\right) \langle v \rangle \{P\}. \ prot\right) * P[\vec{t}/\vec{x}]}{\models \triangleright \operatorname{ses_own} \chi \ s \ (n+1) \ m \left(\operatorname{prot}[\vec{t}/\vec{x}]\right) * \operatorname{ses_idx} \chi \ s \ n \left(v[\vec{t}/\vec{x}]\right)}$

 $\frac{\text{sescrow-recv}}{\text{ses_own }\chi \text{ s }n \text{ }m \text{ }(?(\vec{x}:\vec{\tau}) \langle v \rangle \{P\}. \text{ prot}) * \text{ses_idx }\chi \text{ }\overline{s} \text{ }m \text{ }w}{\text{b} \text{ses_own }\chi \text{ } n \text{ }(\vec{\tau}:\vec{\tau}) \text{ }(v \rangle \{P\}. \text{ prot}) * \text{ses_idx }\chi \text{ }\overline{s} \text{ }m \text{ }w}$

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Derived abstractions may hide the number of laters that is needed to be stripped:

SESCROW-INIT $| \rightsquigarrow \exists \chi. \text{ ses_own } \chi \text{ left } 0 \text{ } 0 \text{ } \text{prot} * \text{ses_own } \chi \text{ right } 0 \text{ } 0 \text{ } \overline{\text{prot}}$ SESCROW-SEND $\frac{\text{ses_own } \chi \text{ } s \text{ } n \text{ } m \left(! \left(\vec{x} : \vec{\tau} \right) \langle v \rangle \{ P \}. \text{ } \text{prot} \right) * P[\vec{t}/\vec{x}]}{\left| \rightarrowtail \text{ ses_own } \chi \text{ } s \text{ } (n+1) \text{ } m \left(\text{prot}[\vec{t}/\vec{x}] \right) * \text{ses_idx } \chi \text{ } s \text{ } n \left(v[\vec{t}/\vec{x}] \right) } \right.$ SESCROW-RECV $\frac{\text{ses_own } \chi \text{ } s \text{ } n \text{ } m \left(?(\vec{x} : \vec{\tau}) \langle v \rangle \{ P \}. \text{ } \text{prot} \right) * \text{ses_idx } \chi \text{ } \overline{s} \text{ } m \text{ } w }{\left| \longmapsto \exists (\vec{v} : \vec{\tau}). \text{ ses_own } \chi \text{ } s \text{ } n \left(m + 1 \right) \left(\text{prot}[\vec{v}/\vec{x}] \right) * w = v[\vec{v}/\vec{x}] * P[\vec{v}/\vec{x}] }$

Derived abstractions may hide the number of laters that is needed to be stripped:

SESCROW-INIT $\mapsto \exists \chi . \texttt{ses_own } \chi \texttt{ left } 0 \texttt{ 0 } \texttt{prot} * \texttt{ses_own } \chi \texttt{ right } 0 \texttt{ 0 } \overrightarrow{\texttt{prot}}$ SESCROW-SEND ses_own χ s n m (! (\vec{x} : $\vec{\tau}$) $\langle v \rangle \{P\}$. prot) * $P[\vec{t}/\vec{x}]$ \mapsto ses_own χ s (n+1) m $(prot[\vec{t}/\vec{x}]) *$ ses_idx χ s n $(v[\vec{t}/\vec{x}])$ SESCROW-RECV ses_own χ s n m (?(\vec{x} : $\vec{\tau}$) $\langle v \rangle$ {P}. prot) * ses_idx χ \vec{s} m w $\mapsto \exists (\vec{v}: \vec{\tau}) \text{ ses_own } \gamma \text{ s } n (m+1) (prot[\vec{v}/\vec{x}]) * w = v[\vec{v}/\vec{x}] * P[\vec{v}/\vec{x}]$

This abstract specificiation pattern is undefinable without the step-taking modality.

$$\longmapsto P \triangleq \forall n. \ \exists \bullet \ n \Rightarrow (\exists \bullet \ n * (\triangleright^{n+1} \exists \bullet \ n+1 \Rightarrow \exists \bullet \ n+1 * P))$$

$$\longmapsto P \triangleq \forall n. \ \exists \ \bullet \ n \Rightarrow (\exists \ \bullet \ n \ast (\triangleright^{n+1} \exists \ \bullet \ n+1 \Rightarrow \exists \ \bullet \ n+1 \ast P))$$

It reads as follows:

• Get the step-taking authority $(X_{\bullet} n)$

$$\longmapsto P \triangleq \forall n. \ \exists \bullet \ n \Rightarrow (\exists \bullet \ n * (\triangleright^{n+1} \exists \bullet \ n+1 \Rightarrow \exists \bullet \ n+1 * P))$$

- Get the step-taking authority $(\mathbb{I}_{\bullet} n)$
- ▶ Take a ghost step (in which *n* may be approximated)

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- Get the step-taking authority $(\mathbb{X}_{\bullet} n)$
- Take a ghost step (in which n may be approximated)
- Give back the step-taking authority (X n)

$$\longmapsto P \triangleq \forall n. \ \exists_{\bullet} \ n \Rightarrow (\exists_{\bullet} \ n * (\triangleright^{n+1} \exists_{\bullet} \ n+1 \Rightarrow \exists_{\bullet} \ n+1 * P))$$

- Get the step-taking authority $(\mathbb{X}_{\bullet} n)$
- Take a ghost step (in which n may be approximated)
- ► Give back the step-taking authority (X_• n)
- ▶ Strip laters according to the authorty (▷ⁿ)

$$\longmapsto P \triangleq \forall n. \ \mathbb{X}_{\bullet} \ n \Rightarrow (\mathbb{X}_{\bullet} \ n * (\triangleright^{n+1} \ \mathbb{X}_{\bullet} \ n+1 \Rightarrow \mathbb{X}_{\bullet} \ n+1 * P))$$

- Get the step-taking authority $(\mathbb{X}_{\bullet} n)$
- Take a ghost step (in which n may be approximated)
- ► Give back the step-taking authority (X_• n)
- ▶ Strip laters according to the authorty (▷ⁿ)
- Get the updated step-taking authority, as a step has been taken $(\mathbb{X}_{\bullet} n)$

$$\longmapsto P \triangleq \forall n. \ \mathbb{X}_{\bullet} \ n \Rightarrow (\mathbb{X}_{\bullet} \ n * (\triangleright^{n+1} \ \mathbb{X}_{\bullet} \ n+1 \Rightarrow \mathbb{X}_{\bullet} \ n+1 * P))$$

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- Take a ghost step (in which local step lower bounds can be updated)

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$$\longmapsto P \triangleq \forall n. \ \mathbb{X}_{\bullet} \ n \Rightarrow (\mathbb{X}_{\bullet} \ n * (\triangleright^{n+1} \ \mathbb{X}_{\bullet} \ n+1 \Rightarrow \mathbb{X}_{\bullet} \ n+1 * P))$$

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- Give back the step-taking authority $(X \cdot n)$
- Show P

$$\longmapsto P \triangleq \forall n. \ \mathbb{X}_{\bullet} \ n \Rightarrow (\mathbb{X}_{\bullet} \ n * (\triangleright^{n+1} \ \mathbb{X}_{\bullet} \ n+1 \Rightarrow \mathbb{X}_{\bullet} \ n+1 * P))$$

It reads as follows:

- Get the step-taking authority $(\mathbb{X}_{\bullet} n)$
- Take a ghost step (in which n may be approximated)
- ► Give back the step-taking authority (X_• n)
- Strip laters according to the authorty (▷ⁿ)
- Get the updated step-taking authority, as a step has been taken $(\mathbb{X}_{\bullet} n)$
- Take a ghost step (in which local step lower bounds can be updated)
- ► Give back the step-taking authority (X n)
- Show P

OBS: details about masks are omitted for brevity sake

The step-taking modality enjoys a mix of the rules for the later modality and the ghost update modality:

Step-intro	$\operatorname{Step-mono}$	$\operatorname{Step-upd}$	$\operatorname{Step-sep-comm}$
Ρ	$P \vdash Q$	$\models \mapsto P$	$\rightsquigarrow P * \rightsquigarrow Q$
$\rightarrow P$	$\longmapsto P \vdash \longmapsto Q$	$\rightarrow P$	$\rightarrow P * Q$

These lets us derive abstract specification patterns on top of each other, without breaking abstraction

A valid concern is that the step-taking modality will become the new later modality

 $\mid \sim n$

The intention is that this wont happen.

Regardless of how later-stripping mechanisms evolved, the step-taking modality should always capture the notion of being able to strip however many laters is available during *one* step!

If multiple step-taking modalities are iterated, that should semantically mean that multiple steps are *intended* to be taken.

Questions?